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■ 1.010 ►► Hexapod PAROS (2)













Key features

Six axes PArallel Robot Operating System

Travel ranges linear 350 x 350 x 80 mm

Travel ranges rotation Rx, Ry 40°, Rz, 100°

Maximum speed 30 mm/sec (leg speed)

Pepeatability in space +/- 5µm

High stiffnes

High dynamic

Pivot point can be set by the customer

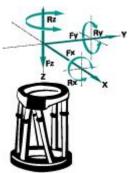
User friendly software

Load capacity central 150 kg

Including software, controller and amplifiers







FACTS

Load Characteristics	Fx (N)	Fy (N)	Fz (N)
DC-B-025 Q	400	400	1500
DC-B-060	50	50	200

SOFTWARE

Calculation of one motion path with collision detection

Pivot Point can be set by the customer

Graphic display of the robot from any view

Digital display of position and orientation

Control in Macro-language stored on own editor

Control by 3D-space-mouse possible

Jog mode

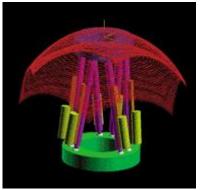
Technical data

Travel Range	
X,Y (mm)	350 x 350
Z (mm)	80
Rx,Ry (°)	40
Rz (°)	100
VelocityRange (mm/sec)	0.01 30*
VelocityRange (°/sec)	0.001 10
BallscrewPitch (mm)	1
Bi-directionalRepeatability (µm)	
X,Y	+/- 5
Z	+/- 5
Bi-directionalRepeatability (µrad)	
Rx,Ry	+/- 75
Rz	+/- 450
Speedmax.	
DC-B-025	
X,Y (mm/sec)	2.5*
Z (mm/sec)	2.5*
Rx,Ry (°/sec)	1.5
Rz (°/sec)	8
DC-B-060	
X,Y (mm/sec)	30*
Z (mm/sec)	30*
Rx,Ry (°/sec)	15
Rz (°/sec)	30
Current(Amps) Voltage (Volts)	
DC-B-025	0.4 42
DC-B-060	1 30
Material	hardened steel, stainless steel, Aluminium black
	anodized
Weight(kg)	21

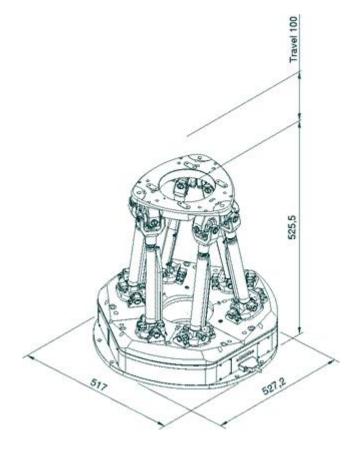
Note: At present with DC-motor - *leg speed

More info: Detailed information, concerning motor and connectors, see: Appendix





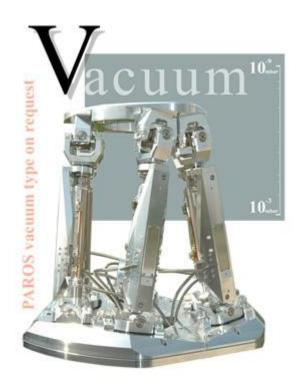
space aera



DC-B-025 DC-B-060

PAROS Ordering information

DC-B-025, gear-head 1 DC-B-060, direct-drive 2



6000-9- 0 0

Founded in 1990, MICOS specializes in the development, manufacturing and marketing of ultra-high precision positioning components and systems for research and industry. We are experts in vacuum, ultra-high vacuum, clean room, and extreme climate environments down to 77 Kelvin.

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MOTION CONTROL = Systems | Positioners | MiniPositioners | DirectDrives | Controllers | ManPositioners | Accessories | Vacuum

MAC PhotonX = Moskito | Albatros | Campus

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